# HeniDes HOLISTIC HUMAN FACTORS AND SYSTEM DESIGN

**OF ADAPTIVE COOPERATIVE HUMAN-MACHINE SYSTEMS** 

# **Task Performance Prediction** for 3D Acquisition



### Domain



## **Motivation**

X-ray angiography is commonly used during minimally invasive procedures. However, the resulting 2-dimensional images provide only limited (2D) information about the anatomy.

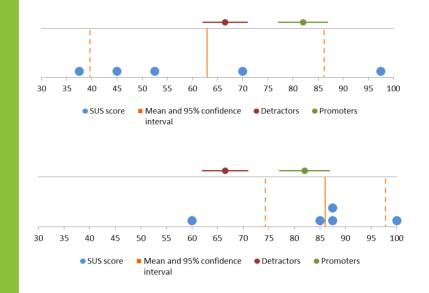
### **Current State: Tailored HF-RTP**



The tailored HF-RTP consists of several tools: A Task Editor to identify interaction tasks between the operator and system. The Human Efficiency Evaluator to model the interaction capabilities of the environment, to demonstrate procedures for common tasks and to execute CASCaS, a cognitive architecture for prediction of human behaviour, allowing analysis of Human Factor Metrics.

# **Results**

#### System Usability Scale



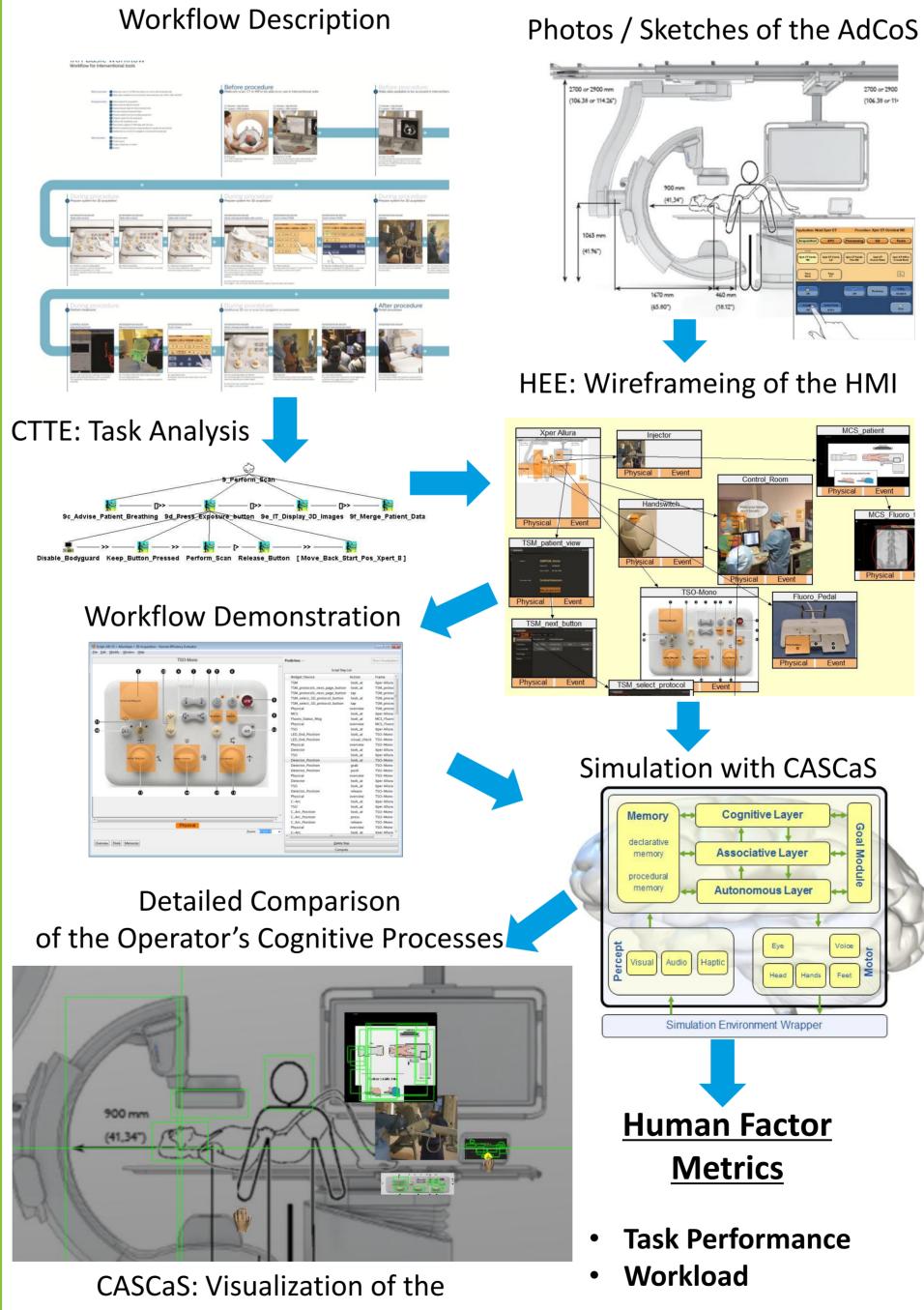
#### **Task Performance** Prediction

File Edit Create Mod	ify Window H	lelp
Tasks	AlluraXper	AlluraXp
3D Acquisition	30,868.0 s	
3D Acquisition_V2		52,021.0 s

rotational acquisition allows **3D** Α visualization of the clinical better treatment, but is very complex, has high **risk** and requires **skilled staff**.

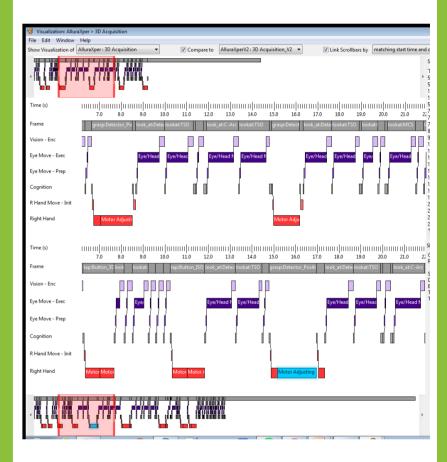
The goal of the 3D Acquisition use case is to help the staff to become more **confident** in acquiring 3D image data by developing novel Human Machine Interaction.

**Applied MTTs** WP2 Wp3 HEE CTTE CASCaS **WP1** 

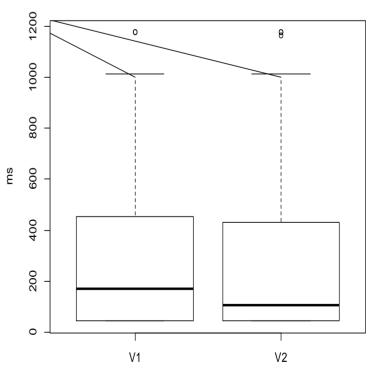


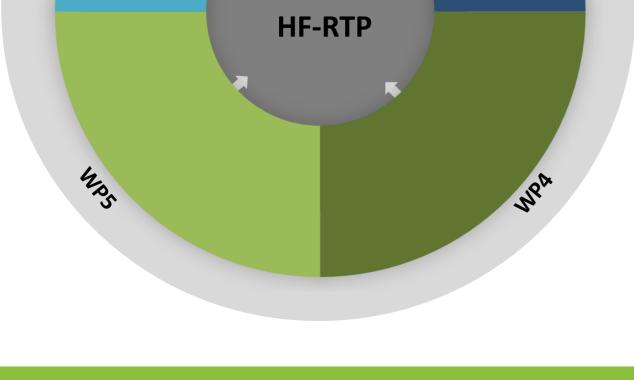
Researchij

#### Workflow Comparison



### Eye & Head **Movements**





virtual Operator

#### Contact

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