

| Humanf Factors Aspect | Implementation into MTT |
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| Situation Awareness | Cognitive models of system objects and their states |
| Perceptual Interference | Overlapping of sensory data (2-D-visual overlapping, sound masking) |
| Distraction | Allocation of attention to salient or cognitive but non-goal-relevant objects |
| Trust in Automation | Tacit trustparameter (a continuous variable) that depends on the ratio of incorrect/correct machine agent decisions |
| Attention: Top-Down | Attention to objects is guided by current goals and the cognitive model about the system's state |
| Attention: Bottom-Up | Dynamic saliency maps |
| Complacency | Tacit parameter related to trust, resulting in more idle scanning and monitoring behaviour. *Onset of complacent behaviour still unclear* |
| Memory | Set of stored items (declarative knowledge) that can be activated for task performance |

| Possible key indicators for HF assessment of AdCos models |
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| Measurement of discrepancies between agents' cognitive models, also wrong inferences |
| Frequency and duration of overlapping information |
| Frequency and duration of attention allocation to irrelevant objects |
| Measurement of discrepancies between agents' cognitive models, also wrong inferences: dynamic threshold for reactions to system warnings; attentional flexibility (flexible vs. idle) |
| Measurement of discrepancies between goals and cognitive models on the one hand and an "ideal representation" on the other hand. |
| Attention allocation to non-goal-related objects (if possible) |
| Measurement of incidents (unwanted events) accompanying complacency |
| Measurement of absent or false declarative knowledge (as an indicator for the systems adaptation to operator expertise); Number of related incidents (close calls) |